M-Theory as a Dynamical System

Georgios Linardopoulos

Institute of Nuclear & Particle Physics National Center for Scientific Research "Demokritos"



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Outline



What is M-theory?





Membranes as dynamical systems

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What is M-theory?

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Quantum field theory

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- What determines the free parameters? Why this particular pattern of gauge fields and multiplets?

General theory of relativity

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- Classical theory breaks down at the (unresolvable) singularities...
- Trying to combine gravity with quantum mechanics (Quantum Gravity) yields a non-renormalizable QFT...
- Naturalness & hierarchy problems: e.g. why is the weak force so much stronger than gravity?

String theory

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- String theory combines the above ideas in a proposal that resolves the divergence problem... The idea is simple: spread out point particles to form strings!



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- However: no experimental verification yet... string phenomenology in its infancy...
M-theory

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Types I, II (IIA, IIB), Heterotic ($\mathfrak{so}(32)$, $\mathsf{E}_8 \times \mathsf{E}_8$).



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- Others have associated "M" with "membranes"...



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- Like strings, membranes can be supersymmetrized... we thus obtain supermembranes...
- There are reasons to believe that membranes (or "M2-branes") are the fundamental objects of 11-dimensional M-theory, just like strings are the fundamental objects of 10-dimensional string theory...

Matrix theory

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- In the large-N limit, the BMN matrix model is again known to reduce to a theory of membranes inside an 11-dimensional planewave background...



Membranes in plane-wave backgrounds

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General setup

• Consider the 11-dimensional maximally supersymmetric plane-wave background:

$$ds^{2} = -2dx^{+}dx^{-} - \left[\frac{\mu^{2}}{9}\sum_{i=1}^{3}x^{i}x^{i} + \frac{\mu^{2}}{36}\sum_{j=1}^{6}y^{j}y^{j}\right]dx^{+}dx^{+} + dx^{i}dx^{i} + dy^{j}dy^{j}, \qquad F_{123+} = \mu.$$

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• The Hamiltonian of a bosonic relativistic membrane in the above background reads

$$H = \frac{T}{2} \int d^2 \sigma \left[p_x^2 + p_y^2 + \frac{1}{2} \left\{ x^i, x^j \right\}^2 + \frac{1}{2} \left\{ y^i, y^j \right\}^2 + \left\{ x^i, y^j \right\}^2 + \frac{\mu^2 x^2}{9} + \frac{\mu^2 y^2}{36} - \frac{\mu}{3} \epsilon_{ijk} \left\{ x^i, x^j \right\} x^k \right]$$

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• The corresponding equations of motion and the Gauß-law constraint are given by:

$$\begin{split} \ddot{x}_{i} &= \left\{ \left\{ x_{i}, x_{j} \right\}, x_{j} \right\} + \left\{ \left\{ x_{i}, y_{j} \right\}, y_{j} \right\} - \frac{\mu^{2}}{9} x_{i} + \frac{\mu}{2} \epsilon_{ijk} \left\{ x_{j}, x_{k} \right\}, \qquad \sum_{i=1}^{3} \left\{ \dot{x}^{i}, x^{i} \right\} + \sum_{j=1}^{6} \left\{ \dot{y}^{j}, y^{j} \right\} = 0 \\ \ddot{y}_{i} &= \left\{ \left\{ y_{i}, y_{j} \right\}, y_{j} \right\} + \left\{ \left\{ y_{i}, x_{j} \right\}, x_{j} \right\} - \frac{\mu^{2}}{36} y_{i}. \end{split}$$

The ansatz

• The following $\mathfrak{so}(3)$ -invariant ansatz automatically satisfies the Gauß-law constraint:

$$\mathbf{x}_i = \tilde{u}_i(\tau) \mathbf{e}_i, \qquad y_j = \tilde{v}_j(\tau) \mathbf{e}_j, \qquad y_{j+3} = \tilde{w}_j(\tau) \mathbf{e}_j, \qquad i, j = 1, 2, 3.$$

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The coordinates e_i are given by

$$(e_1, e_2, e_3) \equiv (\cos \phi \sin \theta, \sin \phi \sin \theta, \cos \theta), \qquad \phi \in [0, 2\pi), \quad \theta \in [0, \pi],$$

satisfy the $\mathfrak{so}(3)$ Poisson algebra and are orthonormal:

$$\{e_i, e_j\} = \epsilon_{ijk} e_k, \qquad \int e_i e_j d^2 \sigma = \frac{4\pi}{3} \delta_{ij}.$$

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- As we will see, the above ansatz leads to an interesting dynamical system with stable and unstable solutions that describe rotating and pulsating membranes of spherical topology.
- Similar work in flat space has previously been carried out by (Axenides-Floratos, 2007).

The Hamiltonian system

• Here's the Hamiltonian of the membrane:

$$\begin{split} H &= \frac{2\pi T}{3} \left[\tilde{p}_{u}^{2} + \tilde{p}_{v}^{2} + \tilde{p}_{w}^{2} + \tilde{u}_{1}^{2} \tilde{u}_{2}^{2} + \tilde{u}_{2}^{2} \tilde{u}_{3}^{2} + \tilde{u}_{3}^{2} \tilde{u}_{1}^{2} + \tilde{r}_{1}^{2} \tilde{r}_{2}^{2} + \tilde{r}_{2}^{2} \tilde{r}_{3}^{2} + \tilde{r}_{3}^{2} \tilde{r}_{1}^{2} + \tilde{u}_{1}^{2} \left(\tilde{r}_{2}^{2} + \tilde{r}_{3}^{2} \right) + \tilde{u}_{2}^{2} \left(\tilde{r}_{3}^{2} + \tilde{r}_{1}^{2} \right) + \\ &+ \tilde{u}_{3}^{2} \left(\tilde{r}_{1}^{2} + \tilde{r}_{2}^{2} \right) + \frac{\mu^{2}}{9} \left(\tilde{u}_{1}^{2} + \tilde{u}_{2}^{2} + \tilde{u}_{3}^{2} \right) + \frac{\mu^{2}}{36} \left(\tilde{r}_{1}^{2} + \tilde{r}_{2}^{2} + \tilde{r}_{3}^{2} \right) - 2\mu \tilde{u}_{1} \tilde{u}_{2} \tilde{u}_{3} \right], \quad \tilde{r}_{j}^{2} \equiv \tilde{v}_{j}^{2} + \tilde{w}_{j}^{2}, \ j = 1, 2, 3. \end{split}$$

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• The Hamiltonian has an obvious $SO(2) \times SO(2) \times SO(2)$ symmetry in the coordinates \tilde{v}_i and \tilde{w}_i so that any solution will preserve three SO(2) angular momenta ℓ_i (i = 1, 2, 3). The kinetic terms are written as:

$$\tilde{p}_{v}^{2} + \tilde{p}_{w}^{2} = \sum_{i=1}^{3} \left(\dot{\tilde{r}}_{i}^{2} + \frac{\ell_{i}^{2}}{\tilde{r}_{i}^{2}} \right)$$

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 What is M-theory?
 Fully asymmetry

 Membranes in plane-wave backgrounds
 Spherically symmetry

 Membranes as dynamical systems
 Conclusions &

Fully asymmetric membrane Spherically symmetric membrane Conclusions & outlook

Membranes as dynamical systems

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Fully asymmetric membrane Spherically symmetric membrane Conclusions & outlook

Fully asymmetric membrane

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The SO(3) sector

• We will only consider the simplest possible case where the SO(6) variables \tilde{v}_i and \tilde{w}_i are set to zero:

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• This is a particular instance of the generalized 3-dimensional Hénon-Heiles potential:

$$V_{\text{H-H}} = \frac{1}{2} \left(u_1^2 + u_2^2 + u_3^2 \right) + K_3 \cdot u_1 u_2 u_3 + K_0 \left(u_1^2 + u_2^2 + u_3^2 \right)^2 + K_4 \left(u_1^4 + u_2^4 + u_3^4 \right),$$

Efstathiou-Sadovskií (2004)

with $K_3 = -9$, $K_0 = -K_4 = 9/4$.

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• Here are the critical points of the SO(3) effective potential:

$$\textbf{u}_0=0, \qquad \textbf{u}_{1/6}=\frac{1}{6}\cdot \left(1,1,1\right), \qquad \textbf{u}_{1/3}=\frac{1}{3}\cdot \left(1,1,1\right).$$

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• The Hamilton equations of motion become:

$$\begin{split} \dot{u}_1 &= p_1, \qquad \dot{p}_1 = -\left[u_1\left(u_2^2 + u_3^2\right) + \frac{u_1}{9} - u_2 u_3\right] \\ \dot{u}_2 &= p_2, \qquad \dot{p}_2 = -\left[u_2\left(u_3^2 + u_1^2\right) + \frac{u_2}{9} - u_3 u_1\right] \\ \dot{u}_3 &= p_3, \qquad \dot{p}_3 = -\left[u_3\left(u_1^2 + u_2^2\right) + \frac{u_3}{9} - u_1 u_2\right]. \end{split}$$

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Radial stability analysis

• By radially perturbing each of the 9 critical points as:

 $u_{i}=u_{i}^{0}+\delta u_{i}\left(t\right) ,$

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we may confirm the conclusion derived above by examining the corresponding Hessian matrix, i.e. that u_0 and $u_{1/3}$ are global minima (positive-definite Hessian) and $u_{1/6}$ is a saddle point (indefinite Hessian):

critical point	eigenvalues λ^2 (#)	stability
u ₀	$-rac{1}{9}$ (3), $-rac{1}{36}$ (6)	center (S)
u _{1/6}	$\frac{1}{18}$ (1), $-\frac{5}{18}$ (2), $-\frac{1}{12}$ (6)	saddle point
u _{1/3}	$-\frac{1}{9}$ (1), $-\frac{4}{9}$ (2), $-\frac{1}{4}$ (6)	center (S)

Axenides-Floratos-G.L. (2017a)

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Angular stability analysis

• We may also perform more general (angular/multipole) perturbations of the following form:

$$x_i(t) = x_i^0 + \delta x_i(t), \qquad i = 1, 2, 3,$$

where δx_i is expanded in spherical harmonics $Y_{jm}(\theta, \phi)$:

$$x_i(t) = \mu u_i(t) e_i, \qquad x_i^0 = \mu u_i^0 e_i, \qquad \delta x_i(t) = \mu \cdot \sum_{j=1}^{\infty} \sum_{m=-j}^{J} \eta_i^{jm}(t) Y_{jm}(\theta, \phi).$$

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• For each of the critical points u_0 , $u_{1/6}$, $u_{1/3}$ we find the eigenvalues (Axenides-Floratos-G.L., 2017b):

$$\begin{split} \mathbf{u}_{0} : \quad \lambda_{P}^{2} &= \lambda_{\pm}^{2} = -\frac{1}{9}, \qquad \lambda_{\theta}^{2} = -\frac{1}{36} \\ \mathbf{u}_{1/6} : \lambda_{P}^{2} &= 0, \qquad \lambda_{+}^{2} = -\frac{1}{36} \left(j+1 \right) \left(j+4 \right), \qquad \lambda_{-}^{2} = -\frac{j \left(j-3 \right)}{36}, \qquad \lambda_{\theta}^{2} = -\frac{1}{36} \left(j^{2}+j+1 \right) \\ \mathbf{u}_{1/3} : \lambda_{P}^{2} &= 0, \qquad \lambda_{+}^{2} = -\frac{1}{36} \left(j+1 \right)^{2}, \qquad \lambda_{-}^{2} = -\frac{j^{2}}{9}, \qquad \lambda_{\theta}^{2} = -\frac{1}{36} \left(2j+1 \right)^{2}, \end{split}$$

with multiplicities $d_P = 2j + 1$, $d_+ = 2j + 3$, $d_- = 2j - 1$ and $d_\theta = 6(2j + 1)$, respectively.

Fully asymmetric membrane Spherically symmetric membrane Conclusions & outlook

Angular stability analysis

• The critical point u_0 (point-like membrane) is obviously stable.

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- In the flat-space limit ($\mu \rightarrow 0$), we recover the results of (Axenides-Floratos-Perivolaropoulos, 2000, 2001).

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Fully asymmetric membrane Spherically symmetric membrane Conclusions & outlook

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• The orbits may be computed from the initial conditions:

$$\dot{u}_{0}(0) = 0, \qquad u_{0}(0) = rac{1}{6} \pm \sqrt{rac{1}{6^{2}} + \sqrt{\mathcal{E}}},$$

where the \pm signs correspond to the right/left side of the double-well potential.



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• Integrating the energy integral we find the solution:

$$u_{0}(t) = \frac{1}{6} \pm \sqrt{\frac{1}{6^{2}} + \sqrt{\mathcal{E}}} \cdot cn\left[\sqrt{2\sqrt{\mathcal{E}}} \cdot t \left| \frac{1}{2} \left(1 + \frac{1}{36\sqrt{\mathcal{E}}} \right) \right]$$

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where only the plus sign should be kept for $\mathcal{E} \geq \mathcal{E}_c$.

• For the critical energy $\mathcal{E} = \mathcal{E}_c$ the homoclinic orbit is obtained:

$$u_0(t) = rac{1}{6} \pm rac{1}{3\sqrt{2}} \cdot \operatorname{sech}\left(rac{t}{3\sqrt{2}}
ight).$$



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• The period as a function of the energy is given in terms of the complete elliptic integral of the first kind:

$$T\left(\mathcal{E}
ight)=2\sqrt{rac{2}{\sqrt{\mathcal{E}}}}\cdot\mathsf{K}\left(rac{1}{2}\left(1+rac{1}{36\sqrt{\mathcal{E}}}
ight)
ight),$$

it becomes infinite for the homoclinic orbit $\mathcal{E} = \mathcal{E}_c$. For more, see e.g. Brizard-Westland (2017).



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Fully asymmetric membrane Spherically symmetric membrane Conclusions & outlook

Conclusions & outlook

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Outlook

• Radial & angular perturbation analysis in the SO(3) × SO(6) case in (Axenides-Floratos-G.L., 2017, 2018).

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Plane-wave backgrounds Membranes in the light-cone gauge Matrix models

Plane-wave backgrounds

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Plane-fronted gravitational waves with parallel rays (pp-waves)

• pp-waves were originally introduced in the so-called Brinkmann coordinates:

$$ds^{2} = H(u, x, y)du^{2} + 2dudv + dx^{2} + dy^{2}.$$

Brinkmann (1925)

• Equivalently, they can be defined as spacetimes that admit a covariantly constant null Killing vector:

$$\nabla_m k_n = 0, \qquad k^n k_n = 0.$$

Ehlers-Kundt (1962)

Plane-wave spacetimes are special pp-waves; the gravitational wave analogue of e/m plane waves...
pp-waves & plane-waves in d + 1 dimensions

• The metric of a pp-wave in d + 1 dimensions is given by:

$$ds^{2} = -2dx^{+}dx^{-} - F(x^{+}, x^{i})dx^{+}dx^{+} + 2A_{j}(x^{+}, x^{i})dx^{+}dx^{j} + g_{jk}(x^{+}, x^{i})dx^{j}dx^{k}, \quad x^{\pm} \equiv \frac{1}{\sqrt{2}}\left(x^{0} \pm x^{d}\right),$$

where i, j = 1, 2, ..., d - 1 and (F, A_j, g_{jk}) are determined from the supergravity equations of motion.

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where i, j = 1, 2, ..., d - 1 and (F, A_j, g_{jk}) are determined from the supergravity equations of motion.

• For $A_j = 0$, $g_{jk} = \delta_{jk}$, pp-waves are α' -exact supergravity solutions: $ds^2 = -2dx^+ dx^- - F(x^+, x^i)dx^+ dx^+ + dx^i dx^i.$

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• Plane-waves are pp-waves for which $F(x^+, x^i) = f_{ij}(x^+)x^ix^j$, $A_j = 0$ and $g_{jk} = \delta_{jk}$: $ds^2 = -2dx^+dx^- - f_{ij}(x^+)x^ix^jdx^+dx^+ + dx^idx^i.$

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- Homogeneous plane-waves have $f_{ij}(x^+) = \mu_{ij}^2$, constant:

$$ds^{2} = -2dx^{+}dx^{-} - \mu_{ij}^{2}x^{i}x^{j}dx^{+}dx^{+} + dx^{i}dx^{i}.$$

pp-waves & plane-waves in d + 1 dimensions

The metric of a pp-wave in d + 1 dimensions is given by:

$$ds^{2} = -2dx^{+}dx^{-} - F(x^{+}, x^{i})dx^{+}dx^{+} + 2A_{j}(x^{+}, x^{i})dx^{+}dx^{j} + g_{jk}(x^{+}, x^{i})dx^{j}dx^{k}, \quad x^{\pm} \equiv \frac{1}{\sqrt{2}}\left(x^{0} \pm x^{d}\right),$$

where i, j = 1, 2, ..., d - 1 and (F, A_j, g_{jk}) are determined from the supergravity equations of motion.

• For
$$A_j = 0$$
, $g_{jk} = \delta_{jk}$, pp-waves are α' -exact supergravity solutions:

$$ds^2 = -2dx^+ dx^- - F(x^+, x^i)dx^+ dx^+ + dx^i dx^i.$$

- Plane-waves are pp-waves for which $F(x^+, x^i) = f_{ij}(x^+)x^i x^j$, $A_j = 0$ and $g_{jk} = \delta_{jk}$: $ds^2 = -2dx^+ dx^- - f_{ij}(x^+)x^i x^j dx^+ dx^+ + dx^i dx^i.$
- Homogeneous plane-waves have $f_{ij}(x^+) = \mu_{ij}^2$, constant: $ds^2 = -2dx^+ dx^- - \mu_{ii}^2 x^i x^j dx^+ dx^+ + dx^i dx^i.$

• Homogeneous and isotropic plane-waves have $\mu_{ij} = \mu$:

$$ds^{2} = -2dx^{+}dx^{-} - \mu^{2}x^{i}x^{i}dx^{+}dx^{+} + dx^{i}dx^{i}.$$

$$(\Box \rightarrow \langle \Box \rangle \langle \Box \rangle$$

Properties of plane waves

- Penrose limit: Any spacetime has a plane-wave as a limit (Penrose, 1975 & Güven, 2000).
- α' -exact solutions of supergravity (with or without flux terms).

Amati-Klimčík (1988), Horowitz-Steif (1990)

• Maximally susy backgrounds of 11-dimensional & IIB sugra (along with flat space and $AdS_{4/5/7} \times S^{7/5/4}$). Figueroa-O'Farrill & Papadopoulos (2003)

• IIB superstring σ model exactly solvable & quantizable on the 10-dimensional maximally susy background. Metsaev (2001), Metsaev-Tseytlin (2002)

• BMN sector of AdS₅/CFT₄: Penrose limit of IIB string theory on AdS₅ × S⁵ \leftrightarrow BMN limit of N = 4 SYM Berenstein-Maldacena-Nastase (2002)

Membranes in the light-cone gauge

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Bosonic membrane in a curved background

Dirac-Nambu-Goto (DNG) action:

$$S_{\rm DNG} = -T \int d\tau d^2 \sigma \left\{ \sqrt{-h} + \dot{X}^m \partial_1 X^n \partial_2 X^r A_{rnm} \left(X \right) \right\}, \qquad T \equiv \frac{1}{\left(2\pi\right)^2 \ell_{11}^3}$$

where (m, n, r, s = 0, ..., 10),

 $h_{ij} \equiv G_{mn}\partial_i X^m \partial_j X^n$ (induced metric) $h \equiv \det h_{ij}$ & $F_{mnrs} = 4\partial_{[m}A_{nrs]}$ (field strength)

and A_{nrs} is the (antisymmetric) 3-form field of 11-dimensional supergravity.

The light-cone gauge

• In the light-cone gauge, we write:

$$X^{\pm} = rac{1}{\sqrt{2}} \left(X^0 \pm X^{10}
ight)$$
 & $X^+ = au.$

Goldstone-Hoppe (1982)

• The light-cone Hamiltonian is then written as follows $(G_{--} = G_{a-} = 0)$:

$$H = T \int d^2 \sigma \Biggl\{ \frac{1}{2} \frac{G_{+-}}{P_{-} - C_{-}} \left[\left(P_a - C_a - \frac{P_{-} - C_{-}}{G_{+-}} G_{a+} \right)^2 + \frac{1}{2} G_{ab} G_{cd} \{ X^a, X^c \} \{ X^b, X^d \} \right] - \frac{1}{2} \frac{P_{-} - C_{-}}{G_{+-}} G_{++} - C_{+} + \frac{1}{P_{-} - C_{-}} \left[C_{-} C_{+-} - \{ X^a, X^b \} P_a C_{+-b} \right] \Biggr\},$$

de Wit, Peeters, Plefka (1998)

where (a, b, c, d = 1, ..., 9),

$$C_{\pm} \equiv C_{\pm ab} - \partial_1 X^a \partial_2 X^b, \quad C_{+-} \equiv -C_{+-a} \{X^-, X^a\}, \quad C_a \equiv -\left(C_{-ab} \{X^b, X^-\} + C_{abc} \partial_1 X^b \partial_2 X^c\right).$$

Poisson bracket

The Poisson bracket is defined as:

$$\{f,g\} \equiv \frac{\epsilon_{rs}}{\sqrt{w(\sigma)}} \partial_r f \, \partial_s g = \frac{1}{\sqrt{w(\sigma)}} \left(\partial_1 f \, \partial_2 g - \partial_2 f \, \partial_1 g\right),$$

where $d^{2}\sigma = \sqrt{w(\sigma)} d\sigma_{1} d\sigma_{2}$. In a flat space-sheet, $w(\sigma) = 1$.

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where $d^2\sigma = \sqrt{w(\sigma)} d\sigma_1 d\sigma_2$. In a flat space-sheet, $w(\sigma) = 1$. In spherical coordinates, $\sqrt{w(\theta)} = \sin \theta$:

 $(\cos\phi\sin\theta,\sin\phi\sin\theta,\cos\theta), \quad \phi\in[0,2\pi), \quad \theta\in[0,\pi].$

Light-cone gauge in the plane-wave background

• In the maximally supersymmetric plane-wave background,

$$\begin{aligned} G_{+-} &= -1, \qquad G_{ab} = \delta_{ab}, \qquad G_{++} = -\frac{\mu^2}{9} \sum_{i=1}^3 x^i x^i - \frac{\mu^2}{36} \sum_{j=1}^6 y^j y^j, \qquad G_{--} = G_{a\pm} = 0 \\ C_{-} &= C_{+-} = C_a = 0, \qquad C_{+} = \frac{\mu}{3} \epsilon_{ijk} \partial_1 x^i \partial_2 x^j x^k, \end{aligned}$$

the light-cone Hamiltonian becomes (for $P_{-} = -1$):

$$H = \frac{T}{2} \int d^2 \sigma \left[p^2 + \frac{1}{2} \left\{ x^i, x^j \right\}^2 + \frac{1}{2} \left\{ y^i, y^j \right\}^2 + \left\{ x^i, y^j \right\}^2 + \frac{\mu^2 x^2}{9} + \frac{\mu^2 y^2}{36} - \frac{\mu}{3} \epsilon_{ijk} \left\{ x^i, x^j \right\} x^k \right].$$

• The corresponding equations of motion and the Gauß law constraint read:

$$\ddot{x}_{i} = \left\{ \left\{ x_{i}, x_{j} \right\}, x_{j} \right\} + \left\{ \left\{ x_{i}, y_{j} \right\}, y_{j} \right\} - \frac{\mu^{2}}{9} x_{i} + \frac{\mu}{2} \epsilon_{ijk} \left\{ x_{j}, x_{k} \right\}, \qquad \sum_{i=1}^{3} \left\{ \dot{x}^{i}, x^{i} \right\} + \sum_{j=1}^{6} \left\{ \dot{y}^{j}, y^{j} \right\} = 0$$

$$\ddot{y}_{i} = \left\{ \left\{ y_{i}, y_{j} \right\}, y_{j} \right\} + \left\{ \left\{ y_{i}, x_{j} \right\}, x_{j} \right\} - \frac{\mu^{2}}{36} y_{i}.$$

Matrix models

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M-theory on a plane wave

• Much of our interest in plane-wave backgrounds derives from the fact that the BMN matrix model,

$$H = \operatorname{Tr}\left[\frac{1}{2}\dot{\mathbf{X}}^{2} - \frac{1}{4}\left[\mathbf{X}^{i}, \mathbf{X}^{j}\right]^{2}\right] + \frac{1}{2} \cdot \operatorname{Tr}\left[\sum_{i=1}^{3} \frac{\mu^{2}}{9} \mathbf{X}_{i}^{2} + \sum_{j=4}^{9} \frac{\mu^{2}}{36} \mathbf{X}_{j}^{2} + \frac{2i\mu}{3} \epsilon_{ijk} \mathbf{X}_{i} \mathbf{X}_{j} \mathbf{X}_{k}\right] + \text{fermions},$$

Berenstein-Maldacena-Nastase (2002)

describes M-Theory on the 11-dimensional maximally supersymmetric plane-wave background:

$$ds^{2} = -2dx^{+}dx^{-} - \left[\frac{\mu^{2}}{9}\sum_{i=1}^{3}x^{i}x^{i} + \frac{\mu^{2}}{36}\sum_{j=1}^{6}y^{j}y^{j}\right]dx^{+}dx^{+} + dx^{i}dx^{i} + dy^{j}dy^{j}, \qquad F_{123+} = \mu.$$

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• Here's the full Hamiltonian of the BMN matrix model (with the fermions):

$$H = H_0 + \frac{1}{2} \cdot \operatorname{Tr}\left[\sum_{i=1}^3 \frac{\mu^2}{9} \mathbf{X}_i^2 + \sum_{j=4}^9 \frac{\mu^2}{36} \mathbf{X}_j^2 - \frac{i\mu}{8} \,\theta^T \gamma_{123} \,\theta + \frac{2i\mu}{3} \,\epsilon_{ijk} \mathbf{X}_i \mathbf{X}_j \mathbf{X}_k\right],$$

where H_0 is just the BFSS Hamiltonian describing M-theory in flat ($\mu = 0$) space:

$$H_{0} = \operatorname{Tr}\left[\frac{1}{2}\dot{\mathbf{X}}^{2} - \frac{1}{4}\left[\mathbf{X}^{i}, \mathbf{X}^{j}\right]^{2} + \theta^{T}\gamma_{i}\left[\mathbf{X}^{i}, \theta\right]\right] \qquad (\operatorname{Banks-Fischler-Shenker-Susskind, 1996).$$

M-theory on a plane wave from membranes

• As shown by Dasgupta, Sheikh-Jabbari and Van Raamsdonk in 2002, the BMN matrix model can be derived by regularizing the light-cone (super)membrane in the 11-dimensional maximally susy plane-wave background.

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